

2021

**모의IMO총회**

The 2021 Mock IMO Assembly

# Proposal to the New Standard of the Degrees of Autonomy for MASS Operations

Team: MASSive

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# Abstract

## New Requirements

Degrees of Autonomy

IMO Instruments

MASS Code

SOLAS  
Convention

for MASS Operations

**SD 2:** Integrate new and advancing technologies in the regulatory framework

**New Output:** Development of a goal-based instrument for maritime autonomous surface ships (MASS)

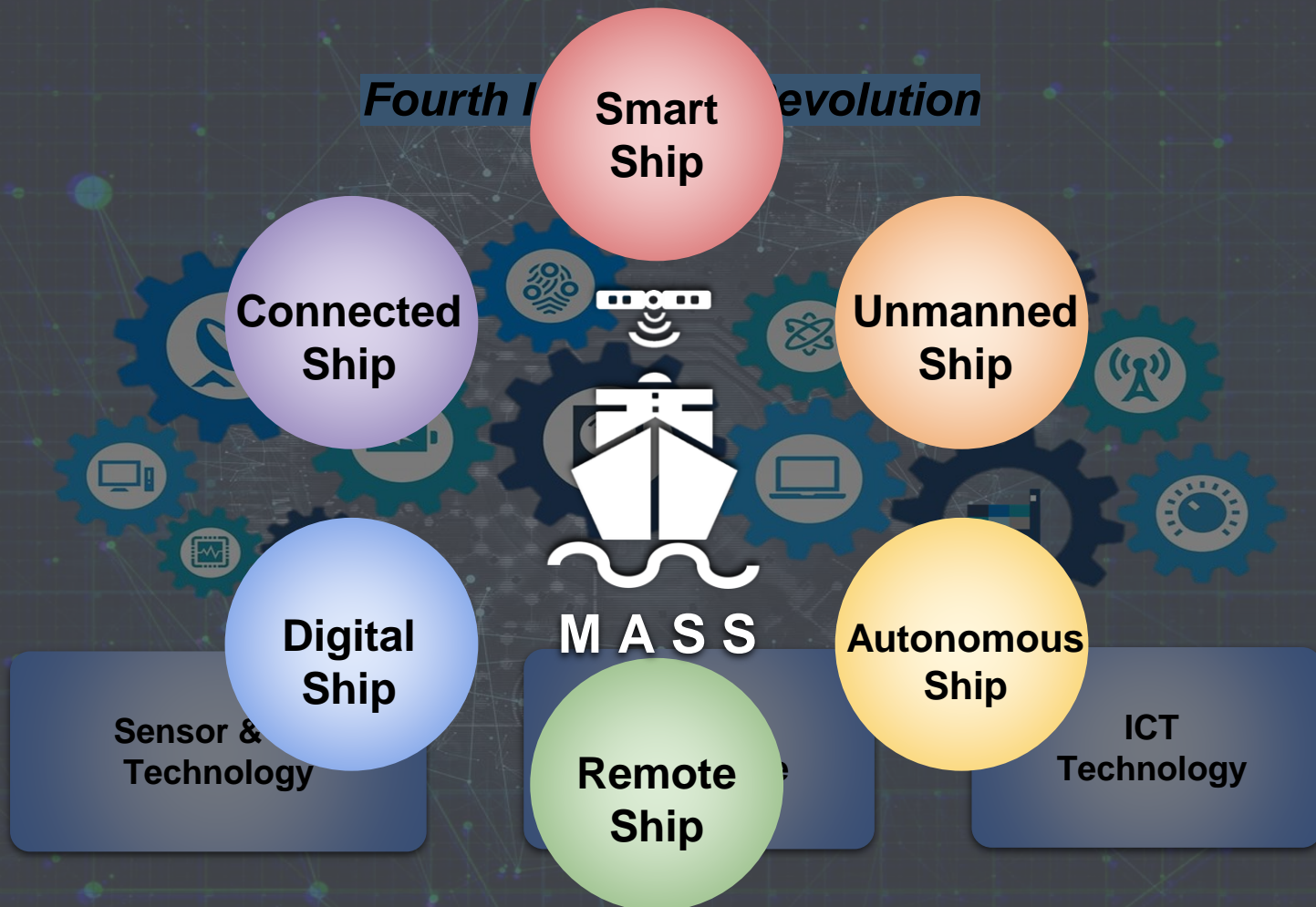


# Introduction

1. Background
2. Trends in the IMO

# Introduction

## Background - Advances in Technology



# Introduction

## Background - Trends in Other Countries

**EU**

- **MUNIN** : Maritime Unmanned Navigation through Intelligence in Networks

**FINLAND**

- **AAWA** : The Advanced Autonomous Waterborne Applications
- **OneSea** : Finnish ecosystems for autonomous maritime transport

**NORWAY**

- **Yara Birkeland** : First fully electric and autonomous container ship
- **AUTOSEA** : Sensor Fusion and collision avoidance for advanced ship
- **ReVolt**

**USA**

- **Mayflower project**
- **ACTUV** : ASW(Anti-Submarine Warfare) Continuous Trail Unmanned Vessel

**CHINA**

- **Green-Dolphin project (2015~)**
- **China Unmanned Cargo Ship Development Alliance**

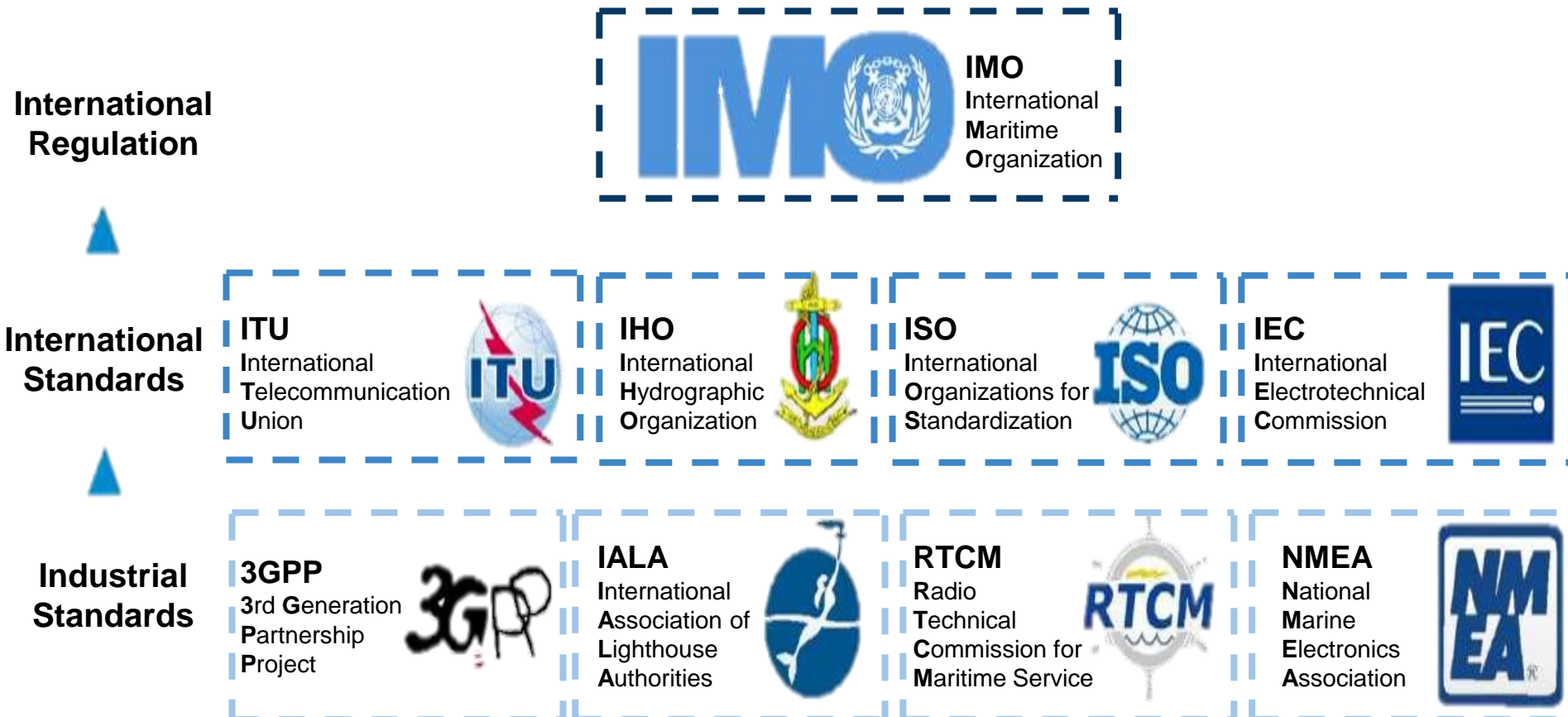
**JAPAN**

- **SSAP** : Smart Ship Application Platform (2012~2017)



# Introduction

## Background - Necessity for IMO Instruments for MASS



# Introduction

## Trends in the IMO - Progress of Discussion

MSC 95  
(‘15. JUN)

The need for guidelines and regulations for the use of MASS emerged.

MSC 98  
(‘17. JUN)

Agreed upon "Regulatory scoping exercise for the use of Maritime Autonomous Surface Ships (MASS)" (~2020)

MSC 99  
(‘18. MAY)

Started to develop a framework for the RSE and defined the aim, the objective, the preliminary definition of MASS and degrees of autonomy.

MSC 100  
(‘18. DEC)

Approved the framework for the RSE, which contained definitions, a methodology consisting of a two-step approach and a plan of work and procedures.



# Introduction

## Trends in the IMO - Progress of Discussion

MSC 101  
(‘19. JUN)

Developed and approved Interim guidelines for MASS trials.  
(MSC.1/Circ.1604)

ISWG/MASS  
(‘19. SEP)

Considered and agreed on the result of the 1st step of the RSE,  
and commenced the 2nd step.

MSC 102  
(‘20. NOV)

Owing to the COVID-19 pandemic,  
MSC 102 deferred consideration of this matter to MSC 103.

MSC 103  
(‘21. MAY)

Finalized the RSE and approved the outcome.

# Introduction

## Expectation of Development for MASS Code

### 6 PRIORITIES FOR FURTHER WORK

6.1 Given the complex and extensive output of the RSE (section 4 and appendix 2), establishing priorities for further work is important. This section has been developed by using the available information in appendix 2, to identify the priorities of work on several issues cutting across a number of individual IMO instruments. The main high-priority items include the need to consider the development of a new instrument, review of terminology and definitions and consideration of high-priority common gaps and themes. It should be noted, however, that the identified priorities are non-exhaustive.

#### Development of a new instrument

6.2 In line with the outcome on the risk of not always addressing MASS operations" in appendix 2, the many common potential gaps and/or themes, which cut across several instruments, could preferably be addressed holistically through a new instrument

(e.g. MASS Code) by addressing every instrument. SOLAS chapters currently contain inconsistencies, confusion and raise potential barriers for the application of existing regulations to conventional ships. Therefore, a MASS instrument, instead of amending individual instruments, may be considered which can be made mandatory by means of amending an existing IMO convention, such as SOLAS. This instrument could preferably be developed following a goal-based approach,<sup>4</sup> in line with the Guidelines developed by the Organization.<sup>5</sup>

6.3 In order to facilitate the operation of MASS at an early stage, establishing interim guidelines for MASS may be beneficial for ensuring safe, secure and environmentally-friendly MASS operations.

Issue	Planned activities and result
1 Consideration of a holistic approach to MASS operations in IMO instruments	
Development of a goal-based MASS instrument	Consideration on how to develop a new MASS instrument and draft amendments to the applicable instruments through which it can be made mandatory
Definition of MASS	Consideration on the need to revise definition and/or degrees and if revision is deemed necessary, agreeing on the definition and/or degrees
Terminology for MASS operations in the IMO	Consideration on the need of supplementing terminology, and if deemed necessary, agreeing on such terminology
High-priority common gaps and themes in relation to MASS operations and IMO regulatory framework <ul style="list-style-type: none"> <li>- Meaning of Master, crew or responsible person</li> <li>- Remote control station/centre</li> <li>- Remote operator designated as seafarer</li> </ul>	Consideration of the high-priority common gaps and themes
Non-mandatory instrument	Consideration of the development of guidelines for MASS operations such as guidelines for installation and guidelines for system application

Table 6: Addressing MASS operations in IMO instruments under the remit of the Maritime Safety Committee

Thus, a new instrument for MASS operations is expected to be developed.

# Analysis of Issue

1. RSE for the Use of MASS
2. The Methodology of the RSE
3. The Outcome of the RSE
4. Top Priority Issue



# Analysis of Issue

## RSE for the Use of MASS

MSC 100/WP.8  
Annex, page 1

### ANNEX

#### FRAMEWORK FOR THE REGULATORY SCOPING EXERCISE

##### Aim

1 The aim of the regulatory scoping exercise is to determine how safe, secure and environmentally sound Maritime Autonomous Surface Ships (MASS) operations might be addressed in IMO instruments.

##### Objective

2 The objective of the regulatory scoping exercise on MASS conducted by the Maritime Safety Committee is to assess the degree to which the existing regulatory framework under its purview may be affected in order to address MASS operations.

##### Glossary

3 For the purpose of the regulatory scoping exercise, "Maritime Autonomous Surface Ship (MASS)" is defined as a ship which, to a varying degree, can operate independent of human interaction.

4 To facilitate the process of the regulatory scoping exercise, the degrees of autonomy are organized as follows:

**Degree one:** *Ship with automated processes and decision support:* Seafarers are on board to operate and control shipboard systems and functions. Some operations may be automated and at times be unsupervised but with seafarers on board ready to take control.

**Degree two:** *Remotely controlled ship with seafarers on board:* The ship is controlled and operated from another location. Seafarers are available on board to take control and to operate the shipboard systems and functions.

**Degree three:** *Remotely controlled ship without seafarers on board:* The ship is controlled and operated from another location. There are no seafarers on board.

**Degree four:** *Fully autonomous ship:* The operating system of the ship is able to make decisions and determine actions by itself.

5 The above list does not represent a hierarchic order. It should be noted that MASS could be operating at one or more degrees of autonomy for the duration of a single voyage.

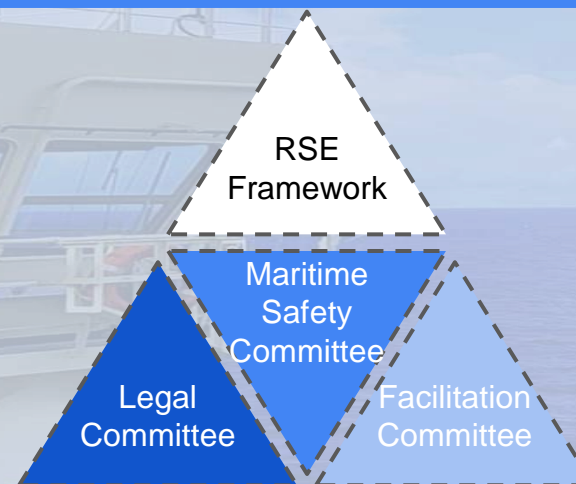
##### Instruments

6 The list of mandatory instruments related to maritime safety and security to be considered as part of the regulatory scoping exercise is set out in appendix 1. These instruments should be reviewed on a regulation or rule level. Subsidiary mandatory instruments established under each parent instrument should also be considered to the level necessary to establish how they will be affected.

I:\MSC\100\WP\MSC 100-WP.8.docx

## Regulatory Scoping Exercise(RSE)

The work to **identify** measures that might arise **when the existing conventions are applied to MASS**, as a preliminary work to develop international standard regulations for the use of MASS.





# Analysis of Issue

## The Methodology of the RSE

### MASS Degrees of Autonomy

Degree One	<b><i>Ship with automated processes and decision support:</i></b> Seafarers are on board to operate and control shipboard systems and functions. Some operations may be automated and at times be unsupervised but with seafarers on board ready to take control.
Degree Two	<b><i>Remotely controlled ship with seafarers on board:</i></b> The ship is controlled and operated from another location. Seafarers are available on board to take control and to operate the shipboard systems and functions.
Degree Three	<b><i>Remotely controlled ship without seafarers on board:</i></b> The ship is controlled and operated from another location. There are no seafarers on board.
Degree Four	<b><i>Fully autonomous ship:</i></b> The operating system of the ship is able to make decisions and determine actions by itself.

# Analysis of Issue

## The Methodology of the RSE

MSC 100/WP.8  
Annex, page 2

7 The review of mandatory instruments should be prioritized. In instruments containing both mandatory and non-mandatory parts, non-mandatory parts may be considered as part of the regulatory scoping exercise, when deemed necessary, to obtain a complete understanding of how the mandatory provisions are affected in order to address MASS operations (see MSC.1/Circ.147, Convention and Code).

### Type and size of ships

8 The application of the regulatory scoping exercise should be restricted to the applicability of the instruments under consideration.

### Methodology

9 As a first step, the regulatory scoping exercise will identify provisions in IMO instruments which, as currently drafted:

- |    |    |   |
|----|----|---|
| .1 | .A | apply to MASS and prevent MASS operations; or   |
| .2 | .B | apply to MASS and do not prevent MASS operations and require no actions; or   |
| .3 | .C | apply to MASS and do not prevent MASS operations but may need to be amended or clarified, and/or may contain gaps; or |
| .4 | .D | have no application to MASS operations.   |

10 Once the first step is completed, a second step will be required to determine the most appropriate way of addressing the issue, inter alia, human element,\* technology and operation.

- |    |      |   |
|----|------|---|
| .1 | .I   | equivalences as provided for by the instruments or developing new interpretations; and/or |
| .2 | .II  | amending existing instruments; and/or   |
| .3 | .III | developing new instruments; or  |
| .4 | .IV  | none of the above as a result of the analysis.  |

11 Appendix 2 provides the template to be used to guide the documentation and, if necessary, present the results of the first step of the regulatory scoping exercise.

### Plan of work and procedures

12 A plan of work and procedures for the regulatory scoping exercise is provided in appendix 3.

\* Refer to resolution A.947(23), Human element vision, principles and goals for the Organization.

### First step: Identification of provisions in IMO instruments

- A. apply to MASS and prevent MASS operations; or
- B. apply to MASS and do not prevent MASS operations and require no actions; or
- C. apply to MASS and do not prevent MASS operations but may need to be amended or clarified, and/or may contain gaps; or
- D. have no application to MASS operations

### Second step: Analysis of the most appropriate way

- I. equivalences as provided for by the instruments or developing new interpretations; and/or
- II. amending existing instruments, and/or
- III. developing new instruments; or
- IV. none of the above as a result of the analysis

# Analysis of Issue

## The Methodology of the RSE

### Example of the RSE regarding Solas chapter III Reg. 17-1 on level 2, 3 MASS

#### Solas ch. III Reg.17-1

1. All ships shall have ship-specific plans and procedures for recovery of persons from the water, taking into account the guidelines developed by the Organization.

1

2

3

4

**SOLAS  
III  
Reg. 17-1**

apply to MASS and prevent MASS operations

apply to MASS, do not prevent MASS operations

apply to MASS and do not prevent MASS operations but may need to be amended or clarified, and /or may contain gaps

have no application to MASS operations

equivalences as provided for by the instruments or developing interpretations

amending existing instruments

developing new instruments

none of the above as a result of the analysis

MASS degrees

Instrument

**First step:**  
identifying instrument

**Second step:**  
analysis

# Analysis of Issue

## The Outcome of RSE

	IMO Instruments	The most appropriate way(s) of addressing MASS operations				
		One	Two	Three	Four	
	Degree of Autonomy	One	Two	Three	Four	ing
Degr	SOLAS chapter XIII	IV	IV	IV	IV	ur
SOL	SOLAS chapter XIV	IV	IV	IV	IV	III
CSS	CSC Code	IV	IV	IV	IV	III
Cas	ESP Code	IV	IV	IV	IV	
III Co	RO Code	IV	IV	IV	IV	
Grain	FTP Code	IV	IV	IV	IV	III
INF C	Polar Code	IV	IV	IV	IV	III
IS Co	LSA Code	IV	IV	IV	IV	
Stand	ISM Code	IV	IV	IV	IV	III
main	ISPS Code	IV	IV	IV	IV	
cover	Standards for the evaluation of scantlings of the transverse watertight vertically corrugated bulkhead between the two foremost cargo holds and for the evaluation of allowable hold loading of the foremost cargo hold	IV	IV	IV	IV	III
	Standards and criteria for side structure of bulk carriers of single-side skin construction	IV	IV	IV	IV	

**Table 5: List of low-priority instruments**



# Analysis of Issue

## The Outcome of RSE

MSC.1/Circ.1638  
Annex, page 14

Issue	Planned activities and result
<b>1 Consideration of a holistic approach to MASS operations in IMO instruments</b>	
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Table 6: Addressing MASS operations in IMO instruments under the remit of the Maritime Safety Committee

### 7 REFERENCES TO THE MATERIAL PRODUCED BEFORE AND DURING THE RSE

#### IMO documents

7.1 A list containing a reference to IMO documents published before and during the RSE is provided in appendix 3.

#### The MASS module of GISIS

7.2 All detailed information, including analysis by the volunteering Member States and comments made by IMO Members have been recorded in the MASS module of GISIS. This web platform is connected to the IMO web accounts, providing access to registered IMO Members only.

I:/Circ/MS/1/MS/1-Circ.1638.docx

## Development of MASS Instruments

1. Definition of MASS
2. Terminology
3. High-priority common gaps and themes
4. Non-mandatory instrument



# Analysis of Issue

## Top Priority Issue

MSC.1/Circ.1638  
Annex, page 5

### Glossary

3 For the purpose of the regulatory scoping exercise, "Maritime Autonomous Surface Ship (MASS)" is defined as a ship which, to a varying degree, can operate independent of human interaction.

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**Degree four:** *Fully autonomous ship:* The operating system of the ship is able to make decisions and determine actions by itself.

1/Circ/MS.1/MS.1-Circ.1638.docx

# Analysis of Issue

## Top Priority Issue

**Degree one:** *Ship with automated processes and decision support:* Seafarers are on board to operate and control shipboard systems and functions. Some operations may be automated and at times be unsupervised but with seafarers on board ready to take control.

**Degree two:** *Remotely controlled ship with seafarers on board:* The ship is controlled and operated from another location. Seafarers are available on board to take control and to operate the shipboard systems and functions.

**Degree three:** *Remotely controlled ship without seafarers on board:* The ship is controlled and operated from another location. There are no seafarers on board.

**Degree four:** *Fully autonomous ship:* The operating system of the ship is able to make decisions and determine actions by itself.

Remain

Severe loopholes exist within the original

OR

Thus,  
The degrees of autonomy should be  
re-evaluated

Re-evaluate



# Problem Analysis

1. Unclear Roles of the Seafarers
2. Unclear Application of Regulations
3. No Concept of Remote Maintenance
4. Absence of Autonomous Mechanisms



# Problem Analysis

## Unclear Roles of the Seafarers

### Degree One

***Ship with automated processes and decision support:*** Seafarers are on board to operate and control shipboard systems and functions.

## 1. **Unclear roles of the seafarers and crew!** **(Degree Two)**

### Degree Four

controlled and operated from another location. There are no seafarers on board.

***Fully autonomous ship:*** The operating system of the ship is able to make decisions and determine actions by itself.

# Problem Analysis

## Unclear Application of Regulations

Degree One

*Ship with automated processes and decision support:* Seafarers

**2. No clear distinctions  
between degree *three* and *four* in their *regulation*!  
(Degree Three and Four: *unmanned* ship)**

Degree Four

*Fully autonomous ship:* The operating system of the ship is able to make decisions and determine actions by itself.

# Problem Analysis

## No Concept of Remote Maintenance

### Degree One

***Ship with automated processes and decision support:*** Seafarers are on board to operate and control shipboard systems and functions.

## 3. **No concept of remote maintenance!** (**Degree Three**)

### Degree Four

~~Controlled and operated from another location. There are no seafarers on board.~~

***Fully autonomous ship:*** The operating system of the ship is able to make decisions and determine actions by itself.

# Problem Analysis

## Absence of Autonomous Mechanisms

4. **Only** considered the **navigation system**  
Who handles the **engine system**?

*In the case of degree 3 and 4, an **electronic machinery** capable of remotely control would be **needed** for the **automation of engines**.*



# Proposal

1. New Standard of the Degrees of Autonomy
2. Requirements for IMO Instruments
3. Conclusion
4. Expected Outcome



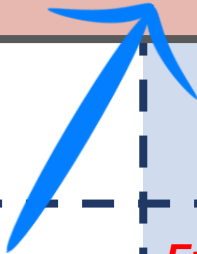
# ***Proposal***

***The New Requirements of  
the Degrees of Autonomy and  
IMO Instruments for MASS Operations***

# Proposal

## New Standard of the Degrees of Autonomy

<u>Operational Requirements - Degree Four</u>	
Seafarer onboard	No
Navigation	By complete AI system
Ship maintenance	Remotely maintenance - examination by system itself, remotely maintenance through robot or drone from the land
The role of the seafarer	Control from the land



**Fully Autonomous Ship:** The operating system of the ship is fully autonomous with **maintenance** of the ship handled remotely. Remote operators are ready in case of emergencies and no seafarers are on board.

**Degree Four**

# Proposal

## Requirements for IMO Instruments - SOLAS Chapter XV

### SOLAS Chapter XV *Safety Measures for MASS Operations at Sea*

1. Definitions
2. Applications
3. Requirements for s
4. The Degrees of Au

should clearly state the adoption of **MASS Code** and the **requirements** for its effect regarding MASS Operations

*MASS Code*







# Proposal

## Requirements for IMO Instruments - MASS Code

### ***The International Code for MASS Operations at Sea***

#### *Table of Contents*

- ☐ Preamble
- ☐ Introduction
  - 1. Goal
  - 2. Definition
  - 3. the Degree of Autonomy
  - 4. Structure of the Code
- ☐ Part I - Safety Measure for MASS Operations
- ☐ Part II - Remote Operation for Navigation
- ☐ Part III - Remote Operation for Machinery
- ☐ Part IV - Fully Autonomous Ship

 <b>Degree One</b>	Ship with automated processes and decision support
 <b>Degree Two</b>	Partially Autonomous Navigation Ship
 <b>Degree Three</b>	Autonomous Navigation Ship
 <b>Degree Four</b>	Fully Autonomous Ship

# Proposal

## Requirements for IMO Instruments - MASS Code

### ***Part I - Safety Measure for MASS Operations***

chapter 1. General

chapter 2. Construction - Ship Structure, Machinery and Electrical Installations, Fire Protection, Fire Detection and Fire Extinction

chapter 3. Life Saving Appliance and Arrangements

chapter 4. Radiocommunications

chapter 5. Safety of Navigation

chapter 6. Cyber Security

chapter 7. Manning and Training



### ***Part II - Remote Operation for Navigation***

chapter 8. Remote Navigation

chapter 9. Remote Control Center/Station



### ***Part III - Remote Operation for Machinery***

chapter 10. Electronic Machinery

chapter 11. Remote maintenance for Machinery



### ***Part IV - Fully Autonomous Ship***

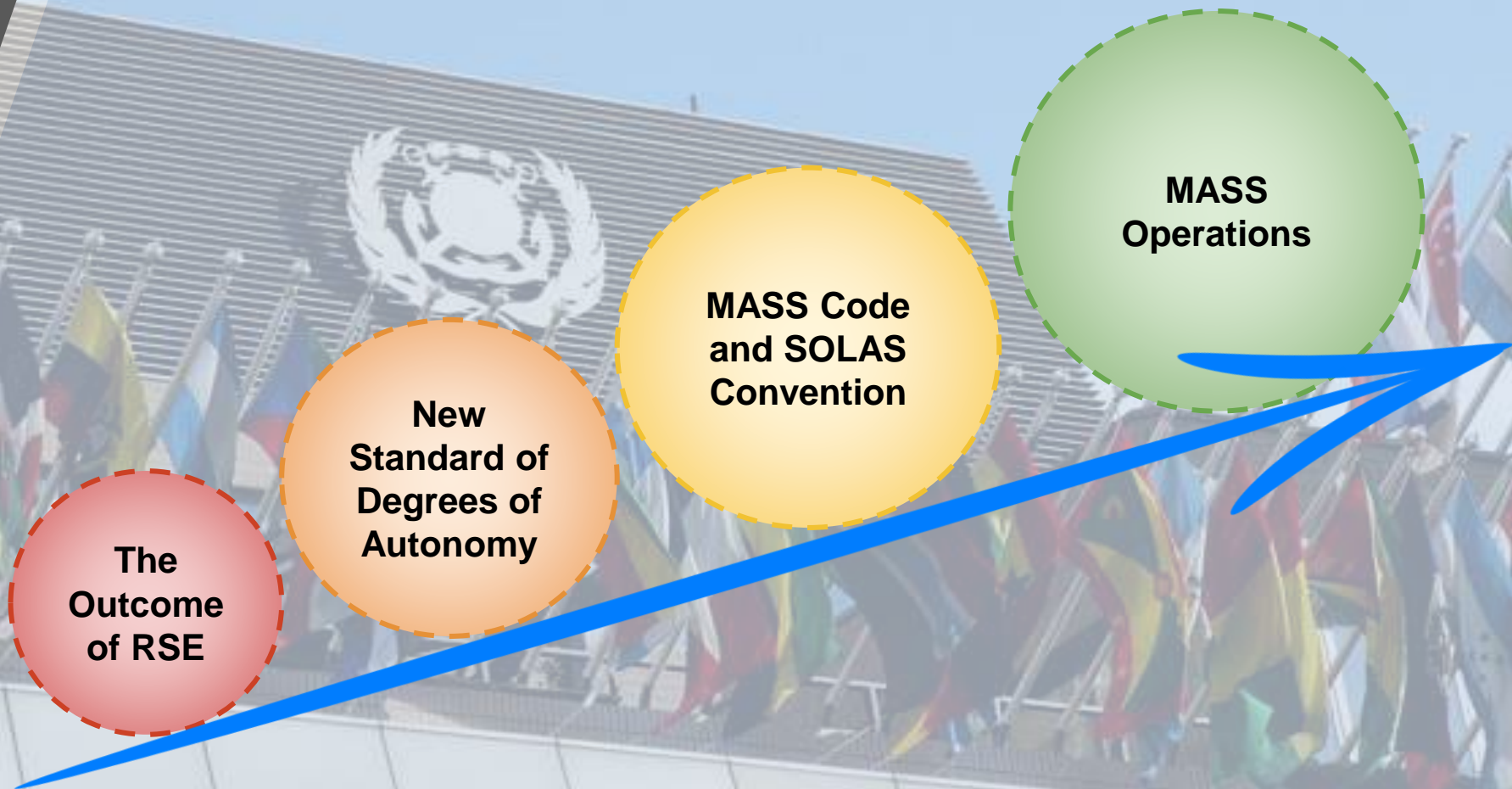
chapter 12. AI Operation System

chapter 13. Autonomous Machinery System



# Proposal

## Conclusion



# Proposal

## Expected Outcome - International/Domestic Prospective

### Domestic Perspective

#### Economy

- ▶ 56 trillion KRW → RIPPLE EFFECT
- ▶ Creation of **420,000 jobs**
- ▶ 103 trillion KRW → front back industry

#### Social

- ▶ accidents by human error **75% ↓**
- ▶ **340 billion KRW** annual environmental benefits by reducing air pollutants

### International Perspective

#### Efficiency

- logistics flow **10%↑**

#### Eco-friendly

- minimize the environmental pollution

#### Safety

- accidents by human error **75% ↓**

#### Economically

- operation cost **22% ↓**

#### Global market scale prediction

- '21(\$80 billion)
- ↓
- '25(\$150 billion)



# Proposal

Expected Outcome - International/Domestic Prospective

Domestic

International



MASS Operations



IMO Instruments



Technologies



***Thank You***